

# ELECTRIC CIRCUITS

## ECSE-2010

Lecture 14.1



## LECTURE 14.1 AGENDA

- Example Problems
- Initial and final values
- Circuit elements in the S-domain

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## CIRCUITS WITH LAPLACE

- Will Do in 2 Steps:
- Method 1
  - First find differential equation
  - Transform to an algebraic equation
  - Take inverse laplace to find  $y(t)$
- Method 2
  - Define s-domain circuits
  - No more differential equations!

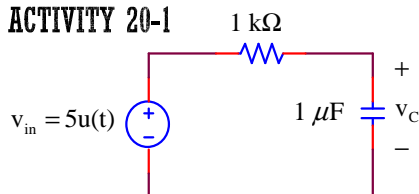


## CIRCUITS WITH LAPLACE

- Same result as solving differential equation:
  - Not clear that this is easier for 1<sup>st</sup> order circuits with switched DC inputs
  - Still have to find differential equation
- Advantage?:
  - Can now solve circuits of ANY order
  - Can now solve circuits with ANY input
  - IF we can find the differential equation



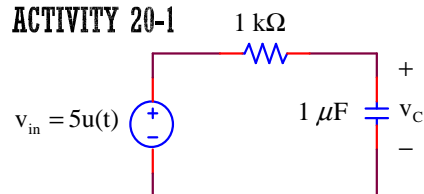
### ACTIVITY 20-1



First Order Circuit  $v_{C0} = 0 \text{ V}$   $v_{CSS} = 5 \text{ V}$   
 Switched DC Input  $v_C(t) = v_{CSS} + (v_{C0} - v_{CSS})e^{-(t-t_0)/\tau}$   
 $\tau = RC = 1 \text{ msec}$   $v_C(t) = 5(1 - e^{-t/\tau}) \quad t \geq 0$



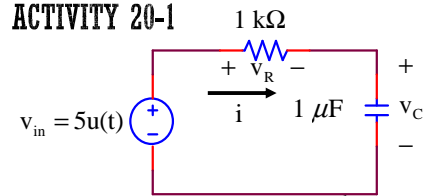
### ACTIVITY 20-1



Find Differential Equation  
 Relating  $v_C(t)$  to  $v_{in}$



### ACTIVITY 20-1



$$v_C + v_R = v_{in} \quad v_R = iR \quad i = C \frac{dv_C}{dt}$$

$$v_C + RC \frac{dv_C}{dt} = v_{in} \quad \frac{dv_C}{dt} + \frac{v_C}{RC} = \frac{v_{in}}{RC} \quad v_C(0^+) = 0$$



### ACTIVITY 20-1

$$\frac{dv_C}{dt} + \frac{v_C}{RC} = \frac{v_{in}}{RC} \quad v_{in} = 5u(t)$$

$$L \left\{ \frac{dv_C}{dt} + \frac{v_C}{RC} \right\} = L \left\{ \frac{5u(t)}{RC} \right\}$$

$$(sV_C(s) - v_C(0^-)) + \frac{V_C(s)}{RC} = \frac{5}{RC} \frac{1}{s}$$

$$(sV_C(s) - v_{C0}) + \frac{V_C(s)}{RC} = \frac{5}{sRC}$$

Algebraic Equation



### ACTIVITY 20-1

$$(sV_C(s) - v_{C0}) + \frac{V_C(s)}{RC} = \frac{5}{sRC}$$

$$V_C(s) \left( s + \frac{1}{RC} \right) = \frac{5}{sRC} + v_{C0}$$

$$V_C(s) = \frac{5/RC}{s(s+1/RC)} + \frac{v_{C0}}{(s+1/RC)}$$



### ACTIVITY 20-1

$$V_C(s) = \frac{5/RC}{s(s+1/RC)} + \frac{v_{C0}}{(s+1/RC)}$$

$$\frac{5/RC}{s(s+1/RC)} = \frac{A_1}{s} + \frac{A_2}{(s+1/RC)}$$

$$A_1 = \left. \frac{5/RC}{(s+1/RC)} \right|_{s=0} = 5$$

$$A_2 = \left. \frac{5/RC}{s} \right|_{s=-1/RC} = -5$$



### ACTIVITY 20-1

$$V_C(s) = \frac{5}{s} + \frac{-5}{s+1/RC} + \frac{v_{C0}}{(s+1/RC)}$$

$$v_C(t) = 5 - 5e^{-t/RC} + v_{C0}e^{-t/RC}$$

$$v_C(t) = 5 + (v_{C0} - 5)e^{-t/RC}$$

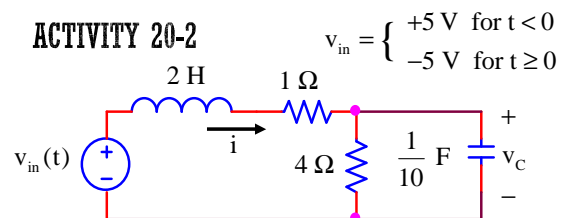
$$v_{C0} = 0; \quad RC = \tau$$

$$v_C(t) = 5(1 - e^{-t/\tau}) \text{ volts} \quad t \geq 0$$

Same as Before



### ACTIVITY 20-2



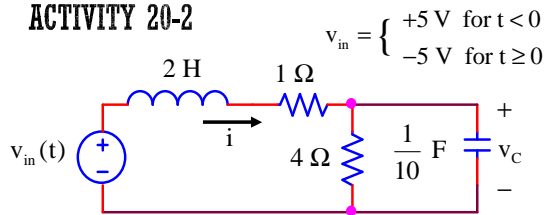
Find  $I(s)$ ,  $V_C(s)$

You do have to find  $v_C(t)$

(e.g. if you like, use Maple or other methods)



### ACTIVITY 20-2



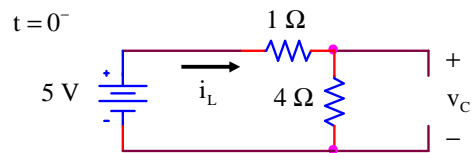
First: Find  $i_L(0^-)$ ,  $v_C(0^-)$  Initial Conditions

Second: Find Differential Equation for  $v_C$

Third: Solve for  $V_C(s)$ ,  $I(s)$



### ACTIVITY 20-2

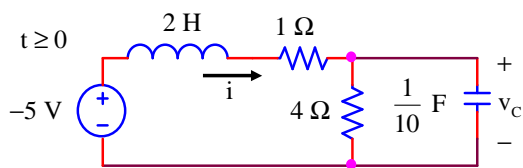


$$i_L(0^-) = 1 \text{ A} \quad i_C(0^-) = 0 = \frac{1}{10} \frac{dv_C}{dt}(0^-)$$

$$v_C(0^-) = 4 \text{ V} \quad \Rightarrow \frac{dv_C}{dt}(0^-) = 0$$



### ACTIVITY 20-2



$$\text{KVL: } v_C + 1(i) + 2 \frac{di}{dt} = -5 \quad \text{KCL: } i = \frac{v_C}{4} + \frac{1}{10} \frac{dv_C}{dt}$$

$$v_C + \left( \frac{v_C}{4} + \frac{1}{10} \frac{dv_C}{dt} \right) + 2 \left( \frac{1}{4} \frac{dv_C}{dt} + \frac{1}{10} \frac{d^2v_C}{dt^2} \right) = -5$$



### ACTIVITY 20-2

$$v_C + \left( \frac{v_C}{4} + \frac{1}{10} \frac{dv_C}{dt} \right) + 2 \left( \frac{1}{4} \frac{dv_C}{dt} + \frac{1}{10} \frac{d^2v_C}{dt^2} \right) = -5$$

$$\frac{1}{5} \frac{d^2v_C}{dt^2} + \frac{6}{10} \frac{dv_C}{dt} + \frac{5}{4} v_C = -5$$

$$\frac{d^2v_C}{dt^2} + 3 \frac{dv_C}{dt} + \frac{25}{4} v_C = -25$$

$$4 \frac{d^2v_C}{dt^2} + 12 \frac{dv_C}{dt} + 25 v_C = -100$$



### ACTIVITY 20-2

$$4 \frac{d^2v_C}{dt^2} + 12 \frac{dv_C}{dt} + 25 v_C = -100$$

$$L \left( \frac{d^2v_C}{dt^2} \right) = s^2 V_C(s) - s v_C(0^-) - \frac{dv_C}{dt}(0^-)$$

$\downarrow$   
 $4s$

$\downarrow$   
 $0$

$$4(s^2 V_C(s) - 4s) + 12(s V_C(s) - 4) + 25 V_C(s) = -\frac{100}{s}$$



### ACTIVITY 20-2

$$4(s^2 V_C(s) - 4s) + 12(s V_C(s) - 4) + 25 V_C(s) = -\frac{100}{s}$$

$$V_C(s)(4s^2 + 12s + 25) = -\frac{100}{s} + 16s + 48$$

$$V_C(s)(4s^2 + 12s + 25) = \frac{-100 + 16s^2 + 48s}{s}$$

$$V_C(s) = \frac{16s^2 + 48s - 100}{s(4s^2 + 12s + 25)}$$



### ACTIVITY 20-2

$$V_c(s) = \frac{16s^2 + 48s - 100}{s(4s^2 + 12s + 25)}$$

$$\text{KCL: } i = \frac{v_c}{4} + \frac{1}{10} \frac{dv_c}{dt}$$

$$L(i) = L\left(\frac{v_c}{4} + \frac{1}{10} \frac{dv_c}{dt}\right)$$

$$I(s) = \frac{V_c(s)}{4} + \frac{1}{10}(sV_c(s) - 4)$$



### ACTIVITY 20-2

$$I(s) = \frac{V_c(s)}{4} + \frac{1}{10}(sV_c(s) - 4)$$

Lots of Algebra Later...

$$I(s) = \frac{4s^2 - 8s - 25}{4s^3 + 12s^2 + 25s}$$



### INITIAL AND FINAL VALUES

- Once we have found  $F(s)$ , the initial and final values of  $f(t)$  can often be found without finding the inverse laplace transform:
  - Initial Value Theorem
  - Final Value Theorem



### INITIAL VALUE THEOREM

$$f(t = 0^+) = f_0 = \lim_{s \rightarrow \infty} sF(s)$$

=> Can Find Initial Value Directly from  $F(s)$

$F(s)$  must be a Proper Rational Fraction

$$(m < n)$$



### INITIAL VALUE THEOREM

Example:

$$F(s) = \frac{2s}{(s^2 + 7s + 12)}$$

$$\Rightarrow f(0^+) = f_0 = \lim_{s \rightarrow \infty} sF(s)$$

$$\Rightarrow f(0^+) = \lim_{s \rightarrow \infty} \frac{2s^2}{(s^2 + 7s + 12)} = 2$$



### FINAL VALUE THEOREM

$$f(t \rightarrow \infty) = f_{ss} = \lim_{s \rightarrow 0} sF(s)$$

=> Can Find Final Value Directly from  $Y(s)$

Limit Must Exist

=> Cannot Use When:

Multiple Poles at  $s = 0$

Poles on Imaginary Axis

Poles in Right Half of  $s$ -plane



## FINAL VALUE THEOREM

Example:

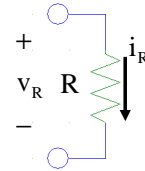
$$F(s) = \frac{2s}{(s^2 + 7s + 12)}$$

$$\Rightarrow f(t \rightarrow \infty) = f_{ss}$$

$$\Rightarrow f(t \rightarrow \infty) = \lim_{s \rightarrow 0} sF(s) = \lim_{s \rightarrow 0} \frac{2s^2}{(s^2 + 7s + 12)} = 0$$



## CIRCUIT ELEMENTS IN S-DOMAIN

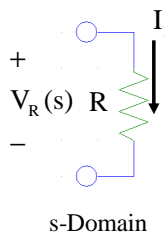


Time Domain

- Time Domain:  
 $v_R(t) = i_R(t)R$ ; Algebraic Equation
- s-Domain:  
 $L\{v_R(t)\} = L\{i_R(t)R\}$   
 $V_R(s) = I_R(s)R \Rightarrow$  Still Algebraic  
 $\Rightarrow$  Resistor still looks like a Resistor  
 $\Rightarrow$  Resistor has an "Impedance" of  $R \Omega$  in s-Domain



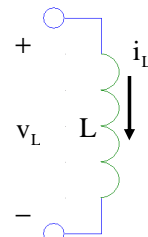
## CIRCUIT ELEMENTS IN S-DOMAIN



- Impedance:  
 $V_R(s) = I_R(s)R$   
 $\frac{V_R(s)}{I_R(s)}$  has units of Ohms  
 $\frac{V_R(s)}{I_R(s)} = Z_R(s) = \text{Impedance of Resistor}$   
 $Z_R(s) = R \Omega$



## CIRCUIT ELEMENTS IN S-DOMAIN



Time Domain

- Time Domain:  
 $v_L = L \frac{di_L}{dt}$ ; Differential Equation
- s-Domain:  
 $L(v_L) = L(L \frac{di_L}{dt})$   
 $\Rightarrow V_L(s) = L\{sI_L(s) - i_L(0^-)\}$   
 $\Rightarrow$  Algebraic Equation



## CIRCUIT ELEMENTS IN S-DOMAIN

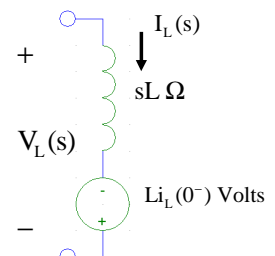
$$V_L(s) = sL I_L(s) - Li_L(0^-)$$

In s-Domain:  
Inductor looks like an "Impedance" of value  $sL \Omega$  in Series with a Voltage Source of  $-Li_L(0^-)$  Volts



## CIRCUIT ELEMENTS IN S-DOMAIN

Model for L in s-Domain

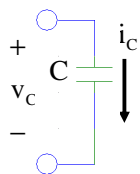


$$V_L(s) = sL I_L(s) - Li_L(0^-)$$



## CIRCUIT ELEMENTS IN S-DOMAIN

Time Domain



- Time Domain:

$$i_C = C \frac{dv_C}{dt}; \text{ Differential Equation}$$

- s-Domain:

$$L(i_C) = L(C \frac{dv_C}{dt})$$

$$\Rightarrow I_C(s) = C \{sV_C(s) - v_C(0^-)\}$$

$$\Rightarrow V_C(s) = \frac{I_C(s)}{sC} + \frac{v_C(0^-)}{s}$$

$$\Rightarrow \text{Algebraic Equation}$$



## CIRCUIT ELEMENTS IN S-DOMAIN

$$V_C(s) = \frac{I_C(s)}{sC} + \frac{v_C(0^-)}{s}$$

In s-Domain:

Capacitor looks like an "Impedance"

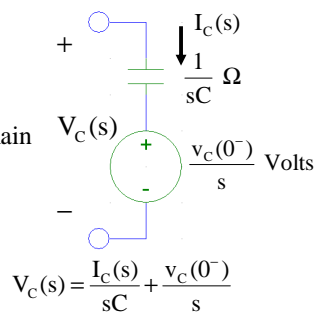
of value  $\frac{1}{sC} \Omega$  in Series with

a Voltage Source of  $\frac{v_C(0^-)}{s}$  Volts

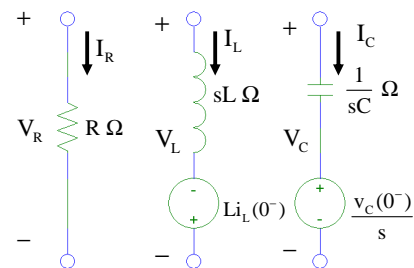


## CIRCUIT ELEMENTS IN S-DOMAIN

Model for C in s-Domain



## CIRCUIT ELEMENTS IN S-DOMAIN



## CIRCUIT ELEMENTS IN S-DOMAIN

For No Initial Stored Energy:

$$v_C(0^-) = i_L(0^-) = 0$$

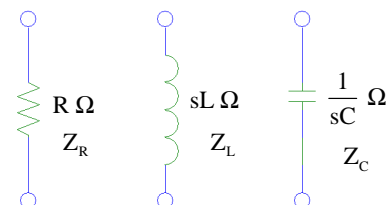
Inductor has "Impedance"  $Z_L = sL \Omega$

Capacitor has "Impedance"  $Z_C = \frac{1}{sC} \Omega$

Resistor ALWAYS has "Impedance"  $Z_R = R \Omega$



## WITH NO INITIAL STORED ENERGY



### **S-DOMAIN CIRCUIT ANALYSIS**

- Input =  $L\{x(t)\} = X(s)$
- Replace all  $i(t)$ ,  $v(t) \rightarrow I(s)$ ,  $V(s)$
- Use s-Domain Models for R, L, C
- Use all techniques developed for Resistive Circuits to find Output in s-Domain =  $Y(s)$
- Take Inverse Laplace Transform of  $Y(s)$  to find Output  $y(t)$
- We'll Practice with Activities 21-1 (today), & 22-1 (Thursday)

